#### Info 2D

# 1 Determination of NCCA in 2 dimensions

We want to consider number conserving CAs in 2 dimensions. There are different possibilities for the neighbourhood, both in size and in shape. To choose a criterium, I will determine all the rules for all the contigous neighbourhoods of sizes 3, 4 and 5, where the cells are said to be contigous if they share a side (**not** just a corner), and for each size, as much states as computationally possible will be considered. The size 2 is not interesting, for in that case the dynamics will be one dimensional, in diagonal, vertical or horizontal lines.

The first subsection (1.1) has the detail of the procedure which is also followed in the rest of this section:

- Listing of the possible shapes.
- Determination of a system of equations for each shape (necessary and sufficient condition).
- Listing the solutions, for each of the computationally feasible numbers of states (Q).
- Discarding of solutions, through considerations of **symmetry**, **conjugation**, and **real size** (the last point means the following: if the rule *ignores* some neighbours, then it may be a rule which has been found in a previous section).
- Description of the resulting set of rules.

## 1.1 Neighbourhood Size 3

The different possibilities of contigous shapes for neighbourhood size 3 are shown in figure 1. Only the shape on the left is interesting (the other is one dimensional).



Fig. 1: Possible shapes for neighbourhoods of size 3

A first thing to notice (which is common to all the NCCAs), is that all states must be quiescent:  $f({i i \atop i}) = i$  $\forall i = 0, ..., Q - 1$ . In particular,  $f({0 0 \atop 0}) = 0$ .

If a thorus is filled with zeroes, but for a region with the configuration  $\binom{ab}{c}$ , we see that any NC rule *f* must satisfy

$$a+b+c = f\begin{pmatrix} 0 & 0 \\ b \end{pmatrix} + f\begin{pmatrix} b & 0 \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ a \end{pmatrix} + f\begin{pmatrix} a & b \\ c \end{pmatrix} + f\begin{pmatrix} c & 0 \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & a \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & c \\ 0 \end{pmatrix}$$

Putting isolated a and c on the thorus, we have

$$a+c = f\begin{pmatrix} a & 0 \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & a \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ a \end{pmatrix} + f\begin{pmatrix} c & 0 \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & c \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ c \end{pmatrix}$$

which may be sustracted from the first equation, obtaining

$$b = f\begin{pmatrix} a & b \\ c \end{pmatrix} + \left[ f\begin{pmatrix} b & 0 \\ 0 \end{pmatrix} - f\begin{pmatrix} a & 0 \\ 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 \\ b \end{pmatrix} - f\begin{pmatrix} 0 & 0 \\ c \end{pmatrix} \right]$$

Now, this is a necessary *and sufficient* condition for f to be number conserving, since if it verifies the equation, then we can add on the two sides, over all the positions of the thorus, and the sum of each of the terms in brackets will cancel, leaving only the sum of the states at one moment (on the left) and at the next moment (on the right).

Q	Rules	New rules
2	3	0
3	9	0
4	36	4
5	195	29

Tab. 1: Number of new rules with neighbourhood of size 3

We can determine all the number conserving rules f for these shapes, for a given number of states Q, by listing the solutions of the respective systems of equations, obtained in each case by replacing all the possible  $a, b, c \in \{0, ..., Q-1\}$ .

The number of solutions for Q = 2, 3, 4, 5 is shown in table 1.1. Some solutions can be discarded: first of all, the ones that ignore one of the positions in the neighbourhood, since the dynamics will be one dimensional. We can also discard rules according to conjugation, where the conjugated rule of f is defined as f'(a,b,c) = Q - 1 - f(Q - 1 - a, Q - 1 - b, Q - 1 - c). And finally, we can discard one of each pair of symmetric rules. What is left is what I call "new rules".



Fig. 2: Some rules, for neighbourhood size 3

#### **Description of the rules**

In most of the rules found here, the behavior after some number of iterations can be summarized as follows: at low density (20%), there is a nearly constant set of ones fixed or shifting on a background of zeroes. For high density (80%), (Q-2)'s shift or remain constant on a background of (Q-1)'s. In between, there works some cancelation law, that can lead to mixed shifts, fixed states or to caotic aspect, on middle density (50%). For some rules, some lines with 0/1 can remain at high density, or lines of

1	0011112200111122001111220011112211222233112222331122223311222233
2	0001000111121112111211122223222311121112
3	00011112111211120001111211121112111222232223
4	00110011112211221122112223322330011001111221122

**Tab. 2:** New rules with neighbourhood of size 3, Q = 4

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1	000111112211122222330001111122111221112
2	000110001100011000111122111221112211122111222223322233222332223322233244222332223322233244222332223324422233222332442223322233244422233222332444222332223322233244222332223322233244422233222332223324422233222332444222332223324442223322233244422233222332223324442223322233222332442223322233244422233222332223324442223322233222332223324442223322233222332223324442223322233222332223322233222332223322233222332444222332444222332223223222332223322233222322232223222322232223222322232223222322232223222322232222
3	00011111220001100011111220001100011111222233333442223322233
4	000110001122233111222223311122111223334422233333440001100011
5	00011111222223311122222330001111122222331112222233000111112222233111222223333344111222223333344111222223333344
6	000110001111122000111112211122111222223311122222331112211122222331112222233222332223333344222333333
7	00011111221112200011111221000111112211122000111112211122222332223311122222332223333443334422233333442223333344222333344
8	000220002211133111331113311133111332224422244
9	000221113311133111331113311133111331113
10	001220012201221123311233112331123311233
11	00001000111112222232223111121111222223333343333411121112
12	000011111211112222232223000011111211112
13	000010000110111121111211112111121111222223222232222322223333343333422223222233334333342222322232223333433334
14	000011111200001111121111200001111120000111112111122222333334222233333423222333334222233333422223333342222333334222233333422223333342222333334222233333422223333422223333422223333342222333342222333334333422223333342222333334222233333422223333342222333334222233333422223333342222333334222233333422223333342222333334222233333422223333342222333334222233333422223333342222333334222233334222233334222233334222233334222233333422223333422223333422223333342222333342222333342222333342222333334222233333422223333422223333342222333242222333342222333342222233334222223333422223222333334222233333422223333422223333422223333422223333422223333422223333422223333422223222223223
15	000010000122223222232222311112111123333433334
16	0000111112222232222300001111122222322223000011111222223222232223
17	0000100011111211112111121111211112222232222322223111121112222232222322223222233334333343333422223222333343333433334
18	00001111121111211112111121111211112111121111
19	000110001111122222332223311122111222223333443334411122111222223333344333440001100011
20	00011111221112222233222330001111122111222223322233111222223324433344000111112211122
21	0001100011000111112211122111221112211122122
22	0001111122000111112210001111122000111112211122223333344222333334433344
23	000110001122233222332223311122111223334433344
24	000110001111122111221112211122111222233222332223311122111222223322233222331112211122222332223322233222332223322233244333443334433344
25	0001111122111221112211122111221112211122111221112211122133222332223322233222332223322233222332223322233222332443334433434
26	001010010111212223223223211212121222323334334334340010100101
27	0010100101010111212112121121211212112122232322323112121121
28	0010111212001011121211212001011121200101112121121
29	001010010111212112121121211212112122323223232323

**Tab. 3:** New rules with neighbourhood of size 3, Q = 5

(Q-1), (Q-2) remain at low ones. Another typical behavior is of diagonal lines moving on a nearly constant background (in figure 2a, the lines are moving up and to the right). Another behavior (rule 4 for Q = 4, 10 for Q = 5; figure 2b) has vertical stripes of lower and higher states. Some exceptional behaviors are those of rule 7, Q = 5, where the diagonal line "combs" the states to build a cluster (different stages in figure 2c-d-e), and rule 23, Q = 5, where the interaction of vertical and horizontal shifts does not cause a cancelation, but a "turning", with nice effects (try density 70%, for instance).

In some cases, in the steady state, it is possible to interpret some transition as a movement of a particle in some direction. But, unfortunately, this is very, very far from actually interpreting the whole rules in terms of particles. More about this, later.

## 1.2 Neighbourhood Size 4

The possible shapes are shown in figure 3. Notice that with the "relaxed" definition of contigous cells, 17 other shapes would be added (I don't understand how or why I missed 9 of them in my original report). Since number 5 is one dimensional, we have four shapes to deal with.



Fig. 3: Possible shapes for neighbourhoods of size 4

#### Shape 1

As before, we fill a thorus but for "one neighbourhood". Adding the states before and after applying



**Tab. 4:** New rules with neighbourhood of size 4, Q = 3, Shape 1

the rule, we have the following condition for the rule to be number conserving:

$$a+b+c+d = f\begin{pmatrix} 0 & 0 \\ 0 & a \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ a & b \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ b & 0 \end{pmatrix} + f\begin{pmatrix} 0 & a \\ 0 & c \end{pmatrix} + f\begin{pmatrix} a & b \\ c & d \end{pmatrix} + f\begin{pmatrix} b & 0 \\ d & 0 \end{pmatrix} + f\begin{pmatrix} 0 & c \\ 0 & 0 \end{pmatrix} + f\begin{pmatrix} c & d \\ 0 & 0 \end{pmatrix} + f\begin{pmatrix} d & 0 \\ 0 & 0 \end{pmatrix}$$

Now, letting some of the variables be zero, we get the following equations:

$$a+b = f\begin{pmatrix} 0 & 0 \\ 0 & a \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ a & b \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ b & 0 \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} + f\begin{pmatrix} a & b \\ 0 & 0 \end{pmatrix} + f\begin{pmatrix} b & 0 \\ 0 & 0 \end{pmatrix}$$
$$a+c = f\begin{pmatrix} 0 & 0 \\ 0 & a \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ a & 0 \end{pmatrix} + f\begin{pmatrix} 0 & a \\ 0 & c \end{pmatrix} + f\begin{pmatrix} a & 0 \\ c & 0 \end{pmatrix} + f\begin{pmatrix} 0 & c \\ 0 & 0 \end{pmatrix} + f\begin{pmatrix} c & 0 \\ 0 & 0 \end{pmatrix}$$
$$a = f\begin{pmatrix} 0 & 0 \\ 0 & a \end{pmatrix} + f\begin{pmatrix} 0 & 0 \\ a & 0 \end{pmatrix} + f\begin{pmatrix} 0 & a \\ 0 & 0 \end{pmatrix} + f\begin{pmatrix} a & 0 \\ 0 & 0 \end{pmatrix}$$

Combining them, we get a necessary and sufficient condition:

$$d = f\begin{pmatrix} a & b \\ c & d \end{pmatrix} + \left[ f\begin{pmatrix} b & 0 \\ d & 0 \end{pmatrix} - f\begin{pmatrix} a & 0 \\ c & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} c & d \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} a & b \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} d & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} b & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} a & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} c & 0 \\ 0 & 0 \end{pmatrix} \right]$$

With (a, b, c, d) ranging over  $\{0, \ldots, Q-1\}^4$ , we obtain for each Q an equation system, whose solutions I listed for Q = 2 and Q = 3. For Q = 4, there are already 27 degrees of freedom, and the listing of the solutions becomes computationally too hard. 4 rules were found for Q = 2 (identity and shifts), and 338 were found for Q = 3.

As before, I discarded rules according to conjugation, symmetry, and non-dependance from some cell of the neighbourhood (for not depending on any of the cells would restrict the rule to the cases of the previous section). 29 were the "new rules" found after this discarding, for Q = 3, and are shown in table 1.2

Shape 2



**Tab. 5:** New rules with neighbourhood of size 4, Q = 3, Shape 2. The first 29 rules are not shown, since they coincide with those on table 1.2.

1	0010010010011121121121121121121121121121
2	001001001112112112001112112001001001112112
3	0010010010011121121121121121121121121121
	· · · · · · · · · · · · · · · · · · ·
т	<b>b</b> 6. New rules with neighbourhood of size $4 - 0 - 3$ Shape 3
-	<b>ab. 0.</b> New fulles with heighbourhood of size 4, $Q = 3$ , shape 5
1	001001001001112112001112112112112112001112112
2	001001001112112112001112112001001001112112
3	001001001001112112112112112112112112112001112112
4	00100111211211211200100100100100101112112
5	001112001001001001112112112001112001112112

**Tab. 7:** New rules with neighbourhood of size 4, Q = 3, Shape 4

The equation is the same as before, and therefore we start with the same solutions. But now there is only one symmetry we can use to discard rules. I also discarded all the rules that ignore any of the 4 positions; ignoring *a* or *d* in  $_{cd}^{ab}$  will produce new rules, but they will be taken into account with shape 4. The number of new rules, then, is 0 (again) for Q = 2, and 112 for Q = 3.

Shape 3

Now the necessary condition is

$$\begin{aligned} a+b+c+d &= \qquad f\begin{pmatrix} 0 & 0 & 0 \\ a \end{pmatrix} + f\begin{pmatrix} 0 & 0 & 0 \\ b \end{pmatrix} + f\begin{pmatrix} 0 & 0 & 0 \\ c \end{pmatrix} + f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} + f\begin{pmatrix} 0 & 0 & 0 \\$$

which in turns leads to

$$a+b = f\begin{pmatrix} 0 & 0 & 0 \\ a \end{pmatrix} + f\begin{pmatrix} 0 & 0 & 0 \\ b \end{pmatrix} + f\begin{pmatrix} 0 & 0 & a \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & a & b \\ 0 \end{pmatrix} + f\begin{pmatrix} a & b & 0 \\ 0 \end{pmatrix} + f\begin{pmatrix} b & 0 & 0 \\ 0 \end{pmatrix}$$
(2)

$$d = f\begin{pmatrix} 0 & 0 & d \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & d & 0 \\ 0 \end{pmatrix} + f\begin{pmatrix} d & 0 & 0 \\ 0 \end{pmatrix} + f\begin{pmatrix} 0 & 0 & 0 \\ d \end{pmatrix}$$
(3)

and with (1)-(2)-(3) we get the necessary and sufficient condition

$$c = f\begin{pmatrix} a & b & c \\ d \end{pmatrix} + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ c \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ d \end{pmatrix} \right] + \left[ f\begin{pmatrix} b & c & 0 \\ 0 \end{pmatrix} - f\begin{pmatrix} a & b & 0 \\ 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} c & 0 & 0 \\ 0 \end{pmatrix} - f\begin{pmatrix} b & 0 & 0 \\ 0 \end{pmatrix} \right]$$

We found 6 solutions for Q = 2, and 163 for Q = 3. Then I proceeded to discard all the rules that didn't consider *a*, *c* or *d* in  $f\begin{pmatrix} a & b & c \\ d & \end{pmatrix}$ ; ignoring *b* was allowed (for the resulting shape hasn't been considered before). Conjugation, and (horizontal) symmetry were also used to discard. No rule survived for Q = 2, and only 3 did for Q = 3.

For this equation, *it was* possible to list the solutions for Q = 4, since there were "only" 18 degrees of freedom. I don't list them here, nor did I include them in the applet, but I have the list; they are a few thousands.

#### Shape 4

Equation and solutions are the same as for shape 3. Now we can't use symmetry to discard. With respect to the names  $a b c \\ d$ , I discarded the rules that ignored a, d, or that ignored  $\{b, c\}$  (for, in that case, the dynamics will be one dimensional, on one or two lines wrapped around the thorus). After discarding, no one rule was left for Q = 2, and 6 did for Q = 3.

### **Description of the rules**



Fig. 4: Some rules, for neighbourhood size 4, shape 1



**Fig. 5:** Some rules, for neighbourhood size 4, shape 2

Q	Shape 1	Shape 2	Shape 3	Shape 4
2	$4 \rightarrow 0$	$4 \rightarrow 0$	$6 \rightarrow 0$	$6 \rightarrow 0$
3	$338 \rightarrow 29$	$338 \rightarrow 112$	$163 \rightarrow 3$	$163 \rightarrow 6$
4	?	?	$97983 \rightarrow 2247$	$97983 \rightarrow 4227$

Tab. 8: Number of rules and new rules for the different shapes, with neighbourhood size 4.

There are too much rules here; let's consider the rules with Q = 3. Starting with shape 1, some rules are found to be similar to those of the previous section (orthogonal shifts, canceling with different effects for middle densities). The new fenomenon is the appeareance of cluster, which may have a fixed form, or change it all the time (figure 4a-b-c are different moments of a same cluster, for rule 2), shifting in some direction, usually with speed 1/2 (in figure 4d, which corresponds to rule 6, the stripe shifts down with that speed). Figure 4e corresponds to rule 21. Some typical cases for shape 2 are given in figure 5, for rules 14, 49, 57, 63, and 71 (a number of rules gives patterns that look random, and are not worth printing, though a movement can be perceived while looking at them running). The few rules found for shapes 3 and 4 are all of the kind "superposition of shifts".

### 1.3 Neighbourhood Size 5

The possible shapes are shown in figure 6. The following equations give the necessary and sufficient conditions for the respective shapes (in some cases, one equation works for two shapes).



Fig. 6: Possible shapes for neighbourhoods of size 5

For shapes 1 and 2:

$$\begin{aligned} f\left(\begin{array}{c}a\\b&c\\d&d\end{array}\right) &= c + \left[f\left(\begin{array}{c}0\\b&c\\d&0\end{array}\right) - f\left(\begin{array}{c}0\\c&d\\d&0\end{array}\right)\right] + \left[f\left(\begin{array}{c}a\\o&c\\d&0\end{array}\right) - f\left(\begin{array}{c}c\\o&e\\d&0\end{array}\right)\right] + \left[f\left(\begin{array}{c}0\\o&d\\d&0\end{array}\right) - f\left(\begin{array}{c}0\\o&d\\d&0\end{array}\right)\right] + \left[f\left(\begin{array}{c}0\\o&d\\d&0\end{array}\right) - f\left(\begin{array}{c}0\\d&d\\d&0\end{array}\right)\right] + \left[f\left(\begin{array}{c}0\\o&d\\d&0\end{array}\right) - f\left(\begin{array}{c}0\\d&d\\d&0\end{array}\right)\right] + \left[f\left(\begin{array}{c}0\\o&d\\d&0\end{array}\right) - 2f\left(\begin{array}{c}0\\d&d\\d&0\end{array}\right)\right] \end{aligned}$$

For shape 3:

$$\begin{split} f \begin{pmatrix} a \\ b c \\ d \\ e \end{pmatrix} &= c + \left[ f \begin{pmatrix} 0 \\ b \\ c \\ 0 \end{pmatrix} - f \begin{pmatrix} 0 \\ c \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} a \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} - f \begin{pmatrix} c \\ 0 \\ 0 \\ d \\ e \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ e \end{pmatrix} - f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ e \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} - f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} - f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[ f \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right] + \left[$$

Q	1	2	3	4	5	6	7	8	9	10	11
2	$7 \rightarrow 0$	$7 \rightarrow 0$	$7 \rightarrow 0$	$9 \rightarrow 0$	$9 \rightarrow 0$	$11 \rightarrow 1$	$11 \rightarrow 2$	$11 \rightarrow 2$	$7 \rightarrow 0$	$23 \rightarrow 0$	$23 \rightarrow 0$
3	$492 \rightarrow 62$	$492 \rightarrow 149$	$690 \rightarrow 97$	$471 \rightarrow 36$	$415 \rightarrow 23$	?→?	?→?	?→?	$630 \rightarrow 27$	?→?	$? \rightarrow ?$

Tab. 9: Number of rules and new rules for the different shapes, with neighbourhood size 5.

For shape 4:

For shape 5:

$$\begin{aligned} f\left(\begin{smallmatrix} a & b \\ b & c & d \\ e & d \\$$

For shape 6:

$$\begin{aligned} f\left(\begin{smallmatrix} a & b \\ c & d \end{smallmatrix}\right) &= e + \left[ f\left(\begin{smallmatrix} a & b \\ 0 & d \end{smallmatrix}\right) - f\left(\begin{smallmatrix} c & c & d \\ 0 & e \end{smallmatrix}\right) \right] + \left[ f\left(\begin{smallmatrix} a & 0 \\ c & 0 \end{smallmatrix}\right) - f\left(\begin{smallmatrix} d & 0 \\ e & 0 \end{smallmatrix}\right) \right] \\ &+ \left[ f\left(\begin{smallmatrix} 0 & 0 \\ 0 & 0 \end{smallmatrix}\right) - f\left(\begin{smallmatrix} 0 & e \\ 0 & 0 \end{smallmatrix}\right) \right] + \left[ f\left(\begin{smallmatrix} d & 0 \\ 0 & 0 \end{smallmatrix}\right) - f\left(\begin{smallmatrix} e & 0 \\ 0 & 0 \end{smallmatrix}\right) \right] + \left[ f\left(\begin{smallmatrix} c & 0 \\ 0 & 0 \end{smallmatrix}\right) - f\left(\begin{smallmatrix} a & 0 \\ 0 & 0 \end{smallmatrix}\right) \right] \end{aligned}$$

For shapes 7 and 8:

For shape 9:

$$f\begin{pmatrix} a & b & c \\ d & e \end{pmatrix} = c + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ d & e \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ a & c \end{pmatrix} \right] + \left[ f\begin{pmatrix} a & b & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} b & c & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & c \\ 0 & e \end{pmatrix} - f\begin{pmatrix} 0 & 0 & a \\ 0 & d \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ a & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ c & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \end{pmatrix} \right] + \left[$$

For shapes 10 and 11:

$$\begin{aligned} f\begin{pmatrix} a & b & c & d \\ e & \end{pmatrix} &= d + \left[ f\begin{pmatrix} a & b & c & 0 \\ 0 & \end{pmatrix} - f\begin{pmatrix} b & c & d & 0 \\ 0 & \end{pmatrix} \right] + \left[ f\begin{pmatrix} b & c & 0 & 0 \\ 0 & \end{pmatrix} - f\begin{pmatrix} c & d & 0 & 0 \\ 0 & \end{pmatrix} \right] \\ &+ \left[ f\begin{pmatrix} c & 0 & 0 & 0 \\ 0 & \end{pmatrix} - f\begin{pmatrix} d & 0 & 0 & 0 \\ 0 & \end{pmatrix} \right] + \left[ f\begin{pmatrix} 0 & 0 & 0 & 0 \\ e & \end{pmatrix} - f\begin{pmatrix} 0 & 0 & 0 & 0 \\ d & \end{pmatrix} \right] \end{aligned}$$

#### **Description of the rules**

The rules found for Q = 2, for shapes 6, 7 and 8, are almost constant, but for some transitions that produce stripes of the kind shown in figure 7a. For Q = 3, the main novelty, in relation to the rules of the previous sections, is the appearance of cluster that remain stable, with activity in their borders (7b). Another new behaviour is the presence of shifts in different directions: in 7c, the "doted lines" above move to the right, while the triangle below moves to the left. In 7d, some lines shift in one direction and some in the other, and in 7e, the two block shift in opposite directions.

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Fig. 7: Some rules, for neighbourhood size 5

### 1.4 General equation for rectangular neighbourhoods

Here I show how to write an equation of the style used before, for any rectangular neighbourhood, for any number of states.

Note that this implies the existence of a system of equations for any neighbourhood (of any shape): just take the equations for the rectangle that covers it, and add the equations to force the resulting rules to ignore the positions which are not part of the shape. This does **not** imply that for any shape, there should be a single expression which generates the whole system of equations, when the variables range over  $0, \ldots, Q - 1$ . Nevertheless, that was the case for all the shapes considered in the previous sections, and I guess that it will be the case for any shape.

(I think it has to do with a symmetry that arises when you write the initial, necessary condition: to write the terms, you move the neighbourhood over a zone of the same shape which is filled with the variables; for each position of the neighbourhood over that zone, there will be a position where neighbourhood and zone are in the same relative positions, but with the roles inverted; the only case where these symmetry doesn't exist, is when the neighbourhood is exactly on the zone, and that's the term you want to conserve. I don't see it clearly, but it must be something like that.)

Let's consider a neighbourhood of n rows and m columns. As before, we take a thorus filled with zeroes, but for a region with the matrix

$$A = \begin{bmatrix} a_{1,1} & \dots & a_{1,m} \\ \vdots & \ddots & \vdots \\ a_{n,1} & \dots & a_{n,m} \end{bmatrix}$$

Since we need to write a lot of matrices, which are all of them submatrices of *A* put in a corner of a matrix of size  $n \times m$ , the rest of which is filled with zeroes, we will use the notation  $\begin{bmatrix} 2,2;2,3\\n,2;n,7 \end{bmatrix}$ , for instance, to represent the image of the matrix

0	 		 0 -
:		:	:
0	 0	0	 0
0	 0	$a_{2,2}$	 $a_{2,7}$
:	:	:	:
0	 0	$a_{n,2}$	 <i>a</i> <sub><i>n</i>,7</sub>

or n,3;n,m, for the image of a matrix filled with zeroes but for the first row, which starts with  $a_{n,3},a_{n,4},\ldots,a_{n,m}$ .

# Info 2D

We start with the necessary condition:

Now, taking  $a_{1,j} = 0$  for all j, we have

Taking  $a_{i,1} = 0$  for all *i*, we have

(4)

(5)

2,2 + 2,2;2,m 2,2;2,m 2,m +2, 2; 2, m2, 2; 2, m2.m3, m3, 2; 3, m3, 2; 3, m2,2;2,m2, 2; 2, m2, mn, 2; n, mn.2:n.mn.m(7) 2,2 n,2 2,2;2,m2, 2; 2, m2, mn,2;n,mn, 2; n, mn, m1, 2; n - 1, mn-1, 2; n-1, mn - 1, mn - 1.2n, 2; n, mn, 2n, 2; n, mn,mn, 2; n, mn,2;n,m *n*,*m n*,2 ++

And finally, taking  $a_{i,1} = 0$  and  $a_{1,j}$  for all i, j, we have

Now, taking (4)-(5)-(6)+(7), we get the following necessary **and sufficient** condition (I was unable to fit it into the page in a way similar to the previous equations...)

$$a_{1,1} = \boxed{\begin{bmatrix} 1,1;1,m\\n,1;n,m \end{bmatrix}} + \sum_{i=1}^{n-1} \sum_{j=1}^{m-1} \left( \begin{array}{c} 1,1;1,j\\i,1;i,j \end{bmatrix} + \begin{array}{c} 2,2;2,j+1\\i+1,2;i+1,j+1 \end{bmatrix} - \begin{array}{c} 1,2;1,j+1\\i,2;i,j+1 \end{bmatrix} - \begin{array}{c} 2,1;2,j\\i+1,1;i+1,j \end{bmatrix} \right) \\ + \sum_{i=1}^{n-1} \left( \left\lfloor \begin{array}{c} 1,1;1,m\\i,1;i,m \end{bmatrix} - \left\lfloor \begin{array}{c} 2,1;2,m\\i+1,1;i+1,m \end{bmatrix} \right) + \sum_{j=1}^{m-1} \left( \overline{\begin{array}{c} 1,1;1,j\\n,1;n,j \end{bmatrix}} - \overline{\begin{array}{c} 1,2;1,j+1\\n,2;n,j+1 \end{bmatrix} \right) \end{array} \right)$$

Unfortunately, the resulting systems are beyond the computational power of my PC (and probably of any PC), for most sizes and numbers of states. The degrees of freedom for different sizes, for small Q, are shown in table 1.4.

For n = m = 2, the solutions were already seen in the previous sections. For Q = 2, n = 2, m = 3, 10 new solutions appeared.



Fig. 8: Rules number 10 and 1, with neighbourhood size 6

### **Description of the rules**

At least at first look, the only rule that seems to show something new is the self-conjugated rule 10, which leads to a stripe wrapped around the thorus, with different curvatures, according to the initial

Q	n	т	Degrees of freedom
2	1	2	1
	1	3	3
	1	4	7
	1	5	15
	1	6	31
	1	7	63
	2	2	5
	2	3	19
	2	4	71
	2	5	271
	3	3	111
3	1	2	2
	1	3	8
	1	4	26
	1	5	80
	2	2	14
	2	3	98
4	2	2	27
5	2	2	44

Tab. 10: Degrees of freedom for different sizes and *Q*.

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1	000000000000000000100111111111100111111
2	00000000000000000010011111111111111001111
3	0000000000000000110011011111111100001111
4	00000000000000000000111111111111111111001111
5	00000000000000001001100111111110011110000
6	0000000000000001101110111111110000110000
7	00000000001001011010001111100110000110000
8	000000000000000101110111111110011000000
9	00000000000000001110111111111111000000110000
10	000000000010001011101001111110011000000

**Tab. 11:** New rules for neighbourhood  $2 \times 3$ , Q = 2

condition. The rest of the rules have rather trivial behaviours; the picture given by rule 1 is new too (with respect to all the rules previously found).